

Tolerating Byzantine processes in distributed systems: using wormholes to reduce the number of replicas

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TheNIS – 2nd Information Security Workshop
IST, Lisboa, July 17th 2007

Navigators group



- Group leader: Paulo Veríssimo
- Currently 9 PhDs (6 faculty, 3 post-docs), 7 PhD students, ? MsC students, ? junior researchers
- Projects: 2 EC STREPs (CRUTIAL, HIDENETS), 1 EC NoE (ReSIST), 1 EC CA (ESFORS), 1 ESA, 5 FCT
- CMU-PT partnership – dual degree MsC in Security and PhD in Informatics
- Research Lines
 - ☞ Fault and Intrusion Tolerance in Open Distributed Systems
 - ☞ Timeliness and Adaptation in Dependable Systems
- <http://www.navigators.di.fc.ul.pt/>

Outline

- Intrusion Tolerance – motivation
- Hybrid system models and Wormholes
- State machine replication
- $2f+1$ atomic multicast
- Consensus
- Conclusions

Intrusion Tolerance – motivation

Motivation for I-T

- Every year thousands of new vulnerabilities appear, zillions of attacks and intrusions
 - ☞ Doing the best we know/can, using security best practices etc. is not enough
- Systems with very high societal importance are becoming “online”
 - ☞ Critical infrastructures: gas, water, electr.,...
 - ☞ Controlled by computers indirectly connected to the Internet

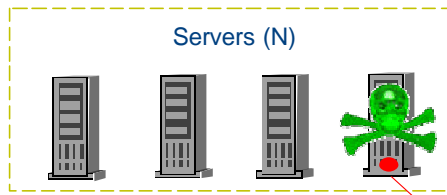
Intrusion Tolerance

- To apply the Fault Tolerance paradigm in the domain of Security
- *Do the best we know to protect systems (prevention)*
- *...but vulnerabilities still remain...*
- *Tolerate intrusions that still occur (tolerance)*

I-T: an example

I-T Distributed Service

Redundancy
Diversity



NFS, DNS,
on-line CA,
Web server,
etc.



0-Day vulnerability

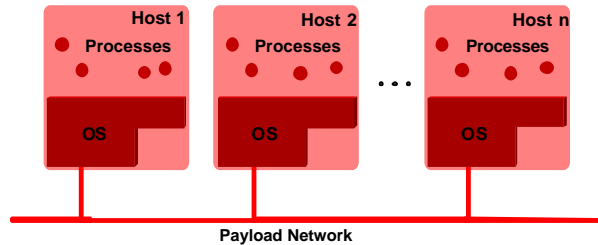


Clients

Hybrid system models and Wormholes

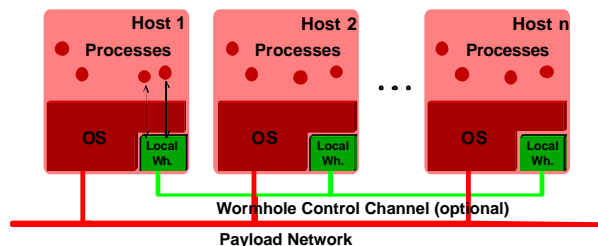
Homogeneous system models

- In Fault and Intrusion Tolerance the system model is usually homogeneous, e.g.:
 - ☞ Asynchronous (no bounds on delays)
 - ☞ Byzantine (or arbitrary) faults



Hybrid system models

- We proposed and are interested on *hybrid* system models. For instance:
 - ☞ Asynchronous/Byzantine as before (red) +
 - ☞ Secure wormhole (green)



Question 1: reasonable model?

- Yes, it models several current systems:
- PCs with Trusted Platform Modules
 - ☞ <https://www.trustedcomputinggroup.org/>
- PCs with SmartCards
- DIY: PCs with virtual machines (Xen, VMWare)
- DIY: PCs with hardware appliances



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Question 2: why model?

- Why not do research about PCs + SmartCards or TPMs or...?
- Science vs. engineering; we want:
 - ☞ *Expressive models of reality*
 - ☞ *Sound theoretical basis for proofs of correctness*
 - ☞ *Enablers of concepts for building new algorithms*
- For practical minds: we can do things that cannot be done with SmartCards or TPMs...
 - ☞ See rest of the talk

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Question 3: model what?

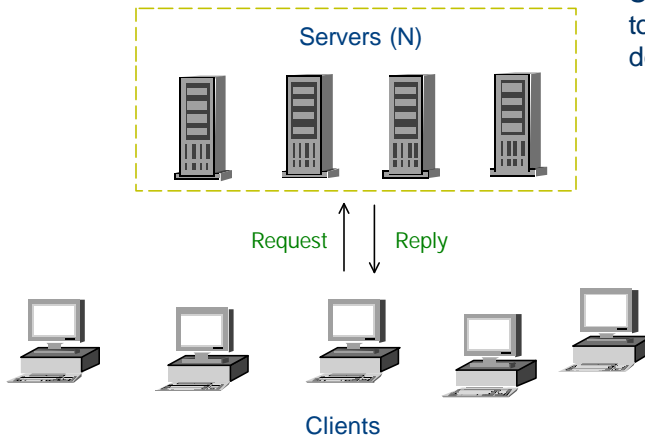
- Not necessarily “*insecure system + secure subsystem*”
 - Some of us have been working with “*untimely system + timely subsystem*”
 - ☞ A. Casimiro, P. Veríssimo, Timely Computing Base
 - on hybrid models and wormholes:

*P. Veríssimo, “Travelling through Wormholes: a new look at Distributed Systems Models”
ACM SIGACT News 2006*
-

State machine replication

SMR basics

I-T Distributed Service



SMR is a mechanism to implement any deterministic service

A server or client is said to be **faulty** if it deviates from its correct behaviour, e.g., because there is an intrusion or it crashes

SMR definition

- Servers are state machines:
 - ☞ state variables, commands
- All correct servers follow the same history of states iff:
 - ☞ *Initial state*: all servers start in the same state
 - ☞ *Agreement*: all servers execute the same commands
 - ☞ *Total order*: all servers execute the commands in the same order
 - ☞ *Determinism*: the same command executed in the same initial state generates the same final state

Atomic multicast

I-T Atomic Multicast

- There is a maximum number f of servers that can be faulty for the system to remain correct
- With an homogeneous system model (asynchronous Byzantine):
 - ☞ Minimum: $N=3f+1$ servers
 - ☞ 4 to tolerate 1 faulty, 7 to tolerate 2 faulty,...
- With a hybrid system model (secure wormhole in servers; not in clients):
 - ☞ Minimum: $N=2f+1$ servers
 - ☞ 3 to tolerate 1 faulty, 5 to tolerate 2 faulty,...
 - ☞ This reduction has a huge impact on the system costs due to the need for diversity

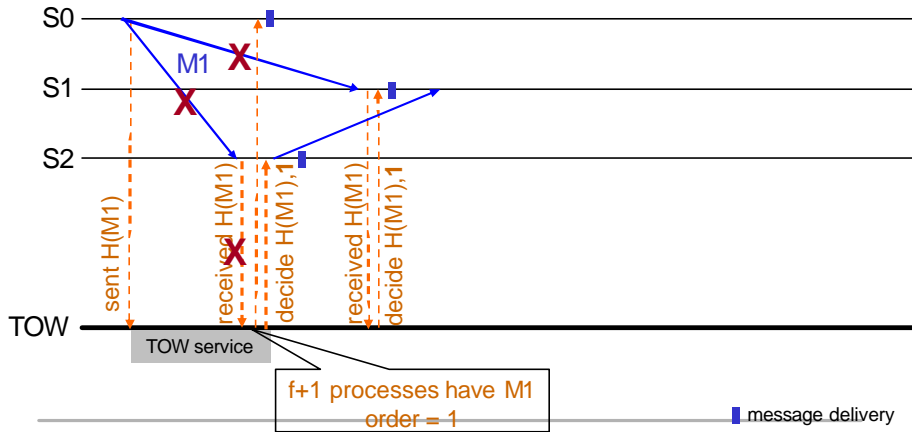
Trusted Ordering Wormhole

- The **TOW** is a wormhole that serves specifically to implement a $2f+1$ I-T atomic multicast
- Provides a single service with two purposes:
 - ☞ Says when a message can be delivered (which is *when $f+1$ servers have it*)
 - ☞ Says the order in which it must be delivered
- API:
 - ☞ TOW_sent – “I sent a message”
 - ☞ TOW_received – “I received a message”
- Output:
 - ☞ TOW_decide – “You can deliver the message, order is η ”

2f+1 Atomic multicast w/TOW

N=3 f=1

H(M) – a collision-resistant hash function



Performance of I-T SMR

- In nice runs

Algorithm	LATENCY			THROUGHPUT		
	ComSteps	SignCP	VerifCP	MsgTot	SignTot	VerifTot
1 Rampart	8	3	$2(n-f) + n$	$4n \oplus 3(n-1)$	$n \oplus (n-1)$	$(n-f)n \oplus (n-f)(n-1)$
2 BFT	5	0	0	$2n \oplus (n-1)(2n-1)$	0	0
3 HQ	4	2	$2(n-f)$	$4n$	$(n+1)$	$(n+1)(n-f)$
4 BFT2F	5	2	$2f$	$2n \oplus (n-1)(2n-1)$	$(n+1) \oplus 0$	$n(2f+1) \oplus 0$
5 Our alg.	5	0	0	$2n \lceil + (n^3 + n^2 - n) \rceil$	0	0

- Bad runs

Algorithm	Bad run	Consequence
1 Rampart	Long communication delays or faulty coordinator	One or more coordinator elections
2 BFT	Same as Rampart	Same as Rampart
3 HQ	Same as Rampart/BFT if there is contention	Change to BFT and run BFT
4 BFT2F	Same as Rampart/BFT	Same as Rampart/BFT
5 Our alg.	Nothing (outside the wormhole)	Not affected (outside the wormhole)

Consensus

Consensus problem

- “How can some distributed processes achieve agreement on a value despite a number of them being faulty?”
 - ☞ Important since related to many other distributed problems
- FLP impossibility result [Fischer et al. 85]
 - ☞ Consensus is impossible to solve deterministically in a completely asynchronous system (with faults)
 - ☞ For the problem to be solved, this result must be “circumvented” (i.e., system model modified): failure detectors, partial synchrony, randomization, wormholes!

Consensus and atomic multicast

- The 2 problems have been proved to be equivalent in several system models
 - ☞ Asynchronous, crash faults, failure detectors
 - ☞ Asynchronous, Byzantine, failure detectors
 - ☞ Asynchronous, Byzantine, randomization
 - ☞ ...
- What about asynchronous Byzantine with TOW?

Consensus and atomic multicast

- Two definitions of Byzantine consensus:
 - ☞ *Validity 1.* If all correct processes propose the same value v , then any correct process that decides, decides v .
 - ☞ *Validity 2.* If a correct process decides v , then v was proposed by some process.
 - ☞ *Agreement.* No two correct processes decide differently.
 - ☞ *Termination.* Every correct process eventually decides.
- It is trivial to use the AM presented to implement consensus with Validity 2
 - ☞ Each process atomic multicast its value
 - ☞ The decision is the first value delivered
- It is simple to see that it is not possible to use the AM presented to obtain consensus with Validity 1

Conclusions

Conclusions (1)

- First solution for intrusion-tolerant state-machine replication in practical distributed systems with only **$2f+1$** replicas
- Interesting impact since each additional replica has a considerable cost
- Circumvents FLP without synchrony assumptions on the asynchronous part of the system
 - ☞ all synchrony is encompassed in the TOW
- Good performance:
 - ☞ Low time complexity
 - ☞ No asymmetric cryptography
 - ☞ No leader elections

Conclusions (2)

- This work showed clear benefits of using a *hybrid system model* and *wormholes*
- Later: necessity of using wormholes (Paulo Sousa)

Questions?

- Some related publications:
 - ☞ M Correia, NF Neves, LC Lung, P Veríssimo. Worm-IT - A Wormhole-based Intrusion-Tolerant Group Communication System. *Journal of Systems & Software*, vol. 80, n. 2, February 2007
 - ☞ P Veríssimo, Travelling through Wormholes: a new look at Distributed Systems Models. *SIGACT News*, vol. 37, n. 1, 2006.
 - ☞ NF Neves, M Correia, P Veríssimo. Solving Vector Consensus with a Wormhole. *IEEE Transactions on Parallel and Distributed Systems*, vol. 16, n.12, Dec. 2005
 - ☞ M Correia, NF Neves, LC Lung, P Veríssimo. Low Complexity Byzantine-Resilient Consensus. *Distributed Computing*, vol. 17, n. 3, March 2005
 - ☞ M Correia, NF Neves, P Veríssimo. **How to Tolerate Half Less One Byzantine Nodes in Practical Distributed Systems**. In Proc. 23rd IEEE Symposium on Reliable Distributed Systems, October 2004 (journal version to appear)
- More info and papers:
 - ☞ <http://www.navigators.di.fc.ul.pt/>
 - ☞ <http://www.di.fc.ul.pt/~mpc/>